

UR20Robot shell

Mounting aid

Preparation:

The robot should be slightly stretched forward -> easier installation of the protective cover

Assembly:

- Place the protective cover around the robot and close it with the Velcro fastener.
- The hook and loop fastener runs lengthwise, facing away from the working area, from the robot.
- Base/arm1; arm1/arm2; arm2/hand axle (axle4) and hand axle (axle6) are connected to each other via rings using ring guards. Close the Velcro fastener on the ring guard
- The outlet of the protective cover on axle 6 has a rubber end.

